

FuPerMod: a Framework for Optimal Data Partitioning for Parallel Scientific Applications on Dedicated Heterogeneous HPC Platforms

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Introduction

- Modern HPC platform = system of heterogeneous devices and links
- How to execute data-parallel applications efficiently?
 - balance the load between processors
 - optimize communications
- **Data partitioning** = load balancing for data-parallel applications
 - performance models of processors

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- **Data partitioning** = load balancing for data-parallel applications
 - performance models of processors
- **Data-parallel scientific applications:** sparse matrices and meshes
 - sparse matrices and meshes can be represented as graphs
 - graph partitioning = optimization of comm. & load balancing
- **Graph partitioning software**
 - ParMETIS, SCOTCH, JOSTLE
 - minimize the communication cost with account for heterogeneity*
 - Zoltan, PaGrid
 - minimize the execution time using a cost function*

Introduction

- **Computational heterogeneity in graph partitioning software**
weights = constants representing the relative speeds of processors
 - must be provided as input - how to find them?
 - const speed is not accurate, especially for dynamic partitioning, self-adaptive applications, hybrid platforms

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- **Computational heterogeneity in graph partitioning software**
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 - const speed is not accurate, especially for dynamic partitioning, self-adaptive applications, hybrid platforms
- **Solution:** a general-purpose framework for data partitioning based on accurate and efficient performance modeling
benchmarks → *models* → *partitioning algorithm* → *partitioning (weights)*
- **Main challenges**
 - performance modeling of interconnected devices and optimized kernels
 - complexity of model-based data partitioning algorithms

Introduction

FuPerMod framework

- Support of wide range of platforms and applications
- Static data partitioning
exhaustive benchmarks → detailed models → static algorithm → partitioning
- Dynamic data partitioning and load balancing
{ benchmark → approx. models → dynamic algorithm → partitioning } +

In this talk

- Use case scenarios
 - Static data partitioning on a hybrid node
 - Dynamic load balancing on a heterogeneous cluster
- FuPerMod programming interface

Outline

- 1 Introduction
- 2 Background
- 3 Static data partitioning on a hybrid node
- 4 Dynamic load balancing on a heterogeneous cluster
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Data partitioning on heterogeneous platforms

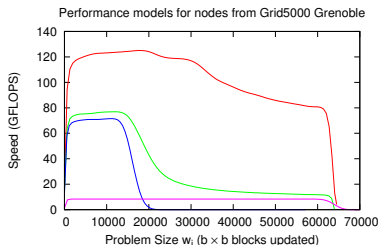
Traditionally, performance is defined by Constant Performance Model (CPM):

- Computed from clock speed or by performing a benchmark
- Computations partitioned proportionally to the speed of processors
- Efficient but simplistic: algorithms may fail to balance the load [1]

Functional Performance Model (FPM):

- Speed as a function of problem size [2]:

$$s(x) = x/t(x)$$
- Realistic performance of hardware and application
- Complex data partitioning algorithms (geometrical, numerical) [3]



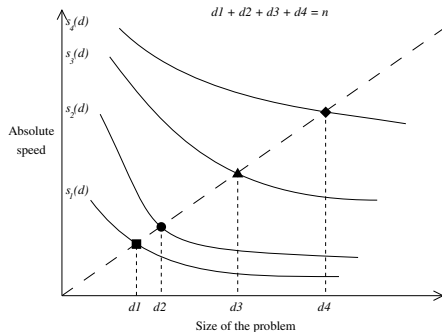
- [1] D. Clarke et al: Dynamic load balancing of parallel iterative routines on platforms with memory heterogeneity (2010)
 [2] A. Lastovetsky et al: Data partitioning with a functional performance model of heterogeneous processors (2007)
 [3] V. Rychkov et al: Using multidimensional solvers for optimal data partitioning on dedicated heterogeneous platforms (2011)

Data partitioning with functional performance models

Load is balanced when:

all processors complete work
within the same time:

$$\begin{cases} t_1(d_1) \approx t_2(d_2) \approx \dots \approx t_p(d_p) \\ d_1 + d_2 + \dots + d_p = N \end{cases}$$



solution lies on a line passing through the origin:

$$d_i/s_i(d_i) = \text{const}$$

- Originally designed for heterogeneous uniprocessor clusters
- Used for static and dynamic data partitioning
- Extended for hybrid multicore multi-GPU nodes [1] and clusters [2]

[1] Z. Zhong et al: Data Partitioning on Heterogeneous Multicore and Multi-GPU Systems Using Functional Performance Models of Data-Parallel Applications (2012)

[2] D. Clarke et al: Hierarchical Partitioning Algorithm for Scientific Computing on Highly Heterogeneous CPU + GPU Clusters (2012)

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Static data partitioning on a hybrid node

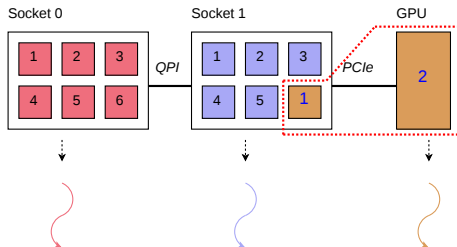
Hardware	CPU (AMD)	GPUs (NVIDIA)	
Architecture	Opteron 8439SE	GF GTX680	Tesla C870
Core Clock	2.8 GHz	1006 MHz	600 MHz
Number of Cores	4×6 cores	1536 cores	128 cores
Memory Size	4×16 GB	2048 MB	1536 MB
Memory Bandwidth	NUMA	192.3 GB/s	76.8 GB/s
Software	multi-threaded	CUDA + out-of-core	
Processes	1 per socket	1 per device	

exhaustive benchmarks $\rightarrow$ *detailed models* $\rightarrow$ *static algorithm* $\rightarrow$ *partitioning*

Configuration of data-parallel application

- No idle compute devices
 - may not be the optimal configuration (out of scope of this study)
- Even load of identical compute devices
 - no evidence that uneven load will improve performance
- One-to-one mapping of processes/threads to compute devices
 - no evidence that many-to-one will improve performance
- Same one-to-one mapping for all runs of the program
 - mapping is not delegated to the operating environment

Configuration of data-parallel application

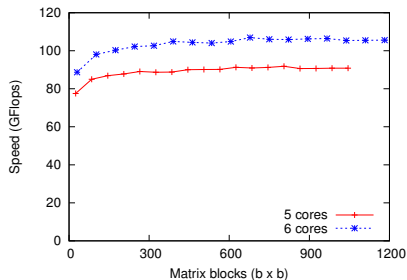
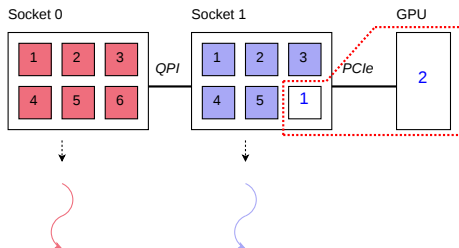


Relatively independent groups of devices: : 6 cores, 5 cores, 1 core + GPU
each group = abstract processor (uni- or multi-processor)

- Cores in a group interfere with each other due to resource contention
- All cores in a group execute the same amount of workload in parallel
- GPU kernel computation time and data transfer time are both included
- Host core for GPU is chosen to maximize data throughput between GPU and NUMA memory

Computation performance models of multicore

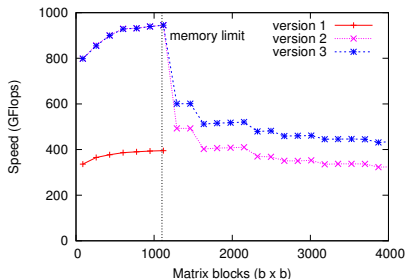
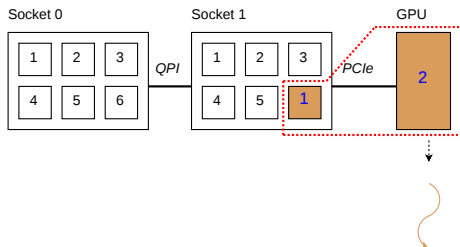
$S_c(x)$: speed of c cores that execute a multi-threaded kernel and share system resources, x units distributed between cores



- $S_5(x)$: 5-threaded kernel on a socket, 1 core idle
- $S_6(x)$: 6-threaded kernel on a socket

Computation performance models of GPU

$g(x)$: combined speed of a GPU and its dedicated core, including data transfers

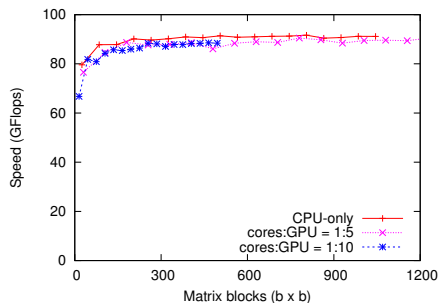


- $g(x)$ (version 1): native CUDA kernel
- $g(x)$ (version 2): accumulate intermediate results + out-of-core
- $g(x)$ (version 3): version 2 + overlap data transfers and kernel executions

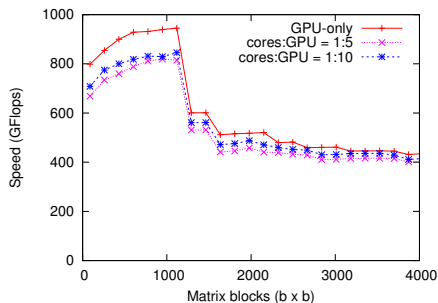
Impact of Resource Contention to Performance Modeling

- CPU and GPU kernel benchmarking simultaneously in a socket
- FPM of multiple cores $s_5(x)$ is barely affected
- FPM of GPU $g(x)$ gets 85% accuracy (speed drops by 7 - 15%)

$s_5(x)$, speed of multiple cores



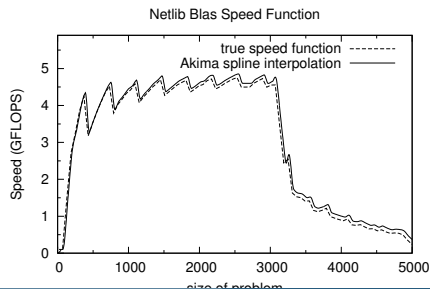
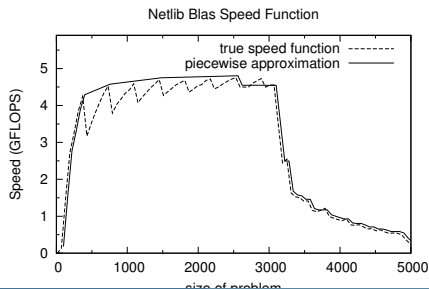
$g(x)$, speed of a GPU



FuPerMod: implemented models

- FPM based on the piecewise linear interpolation of the time function
- FPM based on the Akima spline interpolation of the time function
- CPM (requires only one experimental point)

```
// X = piecewise, interp, constant
fuPerMod_model* model =
    fuPerMod_model_X_alloc(int count, fuPerMod_point* points);
int d = 1000;
double t = model->t(model, d);
double s = d / model->t(model, d);
```



API for computation performance modeling

Computation performance model

```
struct fupermod_model {  
    int count;           // number of data points  
    fupermod_point* points; // data points  
    // approximation of the time function  
    double (*t)(fupermod_model* model, double x);  
    // add a point and update the approximation  
    int (*update)(fupermod_model* model, fupermod_point point);  
};
```

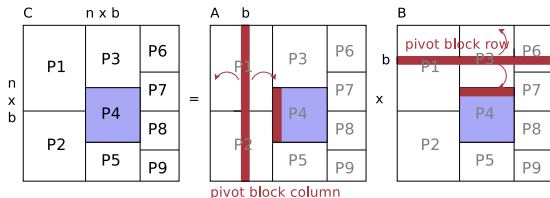
Data point

```
struct fupermod_point {  
    int d;      // problem size  
    double t;   // execution time  
    int reps;   // actual repetitions  
    double ci;  // confidence interval  
};
```

How to obtain data points? → profiling, benchmarking

Computation performance measurement

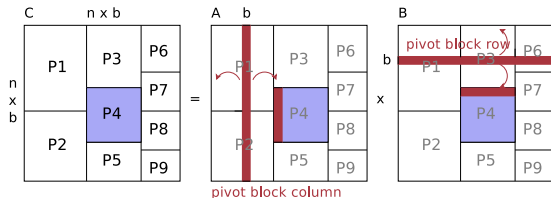
- Parallel matrix multiply: heterogeneous algorithm with minimized volume of communications* *based on SUMMA*



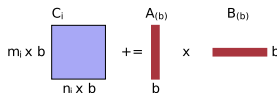
* O. Beaumont et al: Matrix Multiplication on Heterogeneous Platforms (2001)

Computation performance measurement

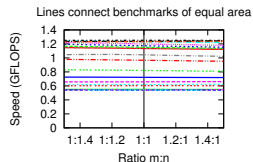
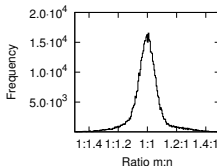
- Parallel matrix multiply: heterogeneous algorithm with minimized volume of communications* *based on SUMMA*



- Computation kernel: panel update *representative for the entire application*



- Speed: function of area *can be measured for square matrices*



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Computation kernel

```
// allocate blocks of matrix, pivot row and column
int initialize(int d, void* params) {
    int m = n = sqrt(d);
    int b = params->b;
    params->C = malloc(m * b * n * b);
    params->WA = malloc(m * b * b);
    params->WB = malloc(n * b * b);
}

// characteristic computation
// dgemm = optimized implementation from ACML (AMD) or CUBLAS (NVIDIA)
int execute(pthread_mutex_t* mutex, void* params) {
    dgemm(params->WA, params->WB, params->C);
}

// deallocate data
int finalize(void* params) {
    free(params->C);
    free(params->WA);
    free(params->WB);
}
```

API for computation performance measurement

Computation kernel

```
// data allocation/deallocation excluded from measurement
// params - application-specific parameters
// mutex - to terminate benchmarking if it takes too long
struct fupermod_kernel {
    int (*initialize)(int d, void* params);
    int (*execute)(pthread_mutex_t* mutex, void* params);
    int (*finalize)(void* params);
};
```

Benchmark for computation kernel

```
int fupermod_benchmark(
    // kernel and problem size
    fupermod_kernel* kernel, int d,
    // statistical parameters
    fupermod_precision precision,
    // to sync some procs if needed
    MPI_Comm comm_sync,
    // returns a data point
    fupermod_point* point
);
```

$\{ \text{benchmark}(\text{kernel}, \text{problem size}) \rightarrow \text{point} \} + \rightarrow \text{model}$

FuPerMod: implemented static partitioning algorithms

- geometrical algorithm based on the piecewise-linear FPMs
- numerical algorithm based on the Akima-spline FPMs
- basic algorithm based on CPMs

```
// X = geometric, multiroot, basic
int fupermod_partition_X(
    int size, fupermod_model** models, fupermod_dist* dist);
```

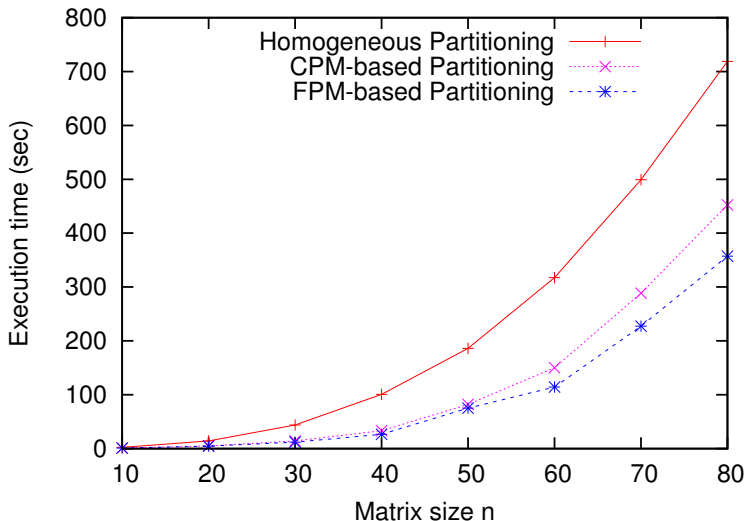
Partitioning

```
struct fupermod_dist {
    int D;      // total problem size
    int size;   // number of procs
    fupermod_part* parts;
};

struct fupermod_part {
    int d;      // data chunk
    double t;   // execution time
};
```

exhaustive benchmarks → detailed models → static algorithm → partitioning

Static data partitioning: experiments



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Dynamic load balancing on a heterogeneous cluster

Iterative routine (Jacobi method): $x^{k+1} = f(x^k)$, $k = 0, 1, \dots$

```
MPI_Comm comm;
// Jacobi data: partitioned matrix/vectors
double *A = ..., *b = ..., *x = ...;
// main loop
while (error > eps) {
    // iteration of Jacobi method
    jacobi_iterate(comm, A, b, x, &error);
}
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while (error > eps) {
    // redistribution of Jacobi data
    jacobi_redistribute(comm, A, b, x, end - start);
    // iteration of Jacobi method
    gettimeofday(&start);
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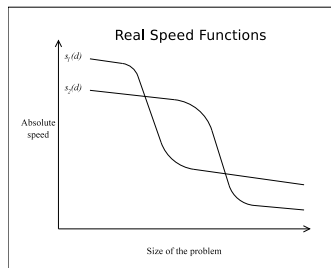
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}
```

$\{ \text{benchmark} \rightarrow \text{approx. models} \rightarrow \text{dynamic algorithm} \rightarrow \text{partitioning} \} +$

Dynamic FPM-based data partitioning

Functional performance models can be built:

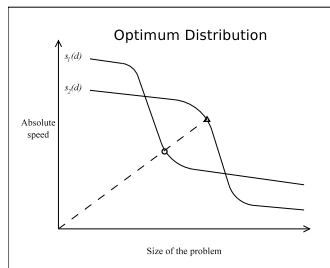
- exhaustively in advance
- dynamically at run time



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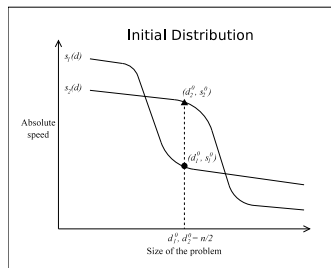


Dynamic FPM-based data partitioning

Functional performance models can be built:

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Initial: point $(n/p, s_i^0)$ with speed $s_i^0 = \frac{n/p}{t_i(n/p)}$
 first function approximation $s_i'(x) \equiv s_i^0$

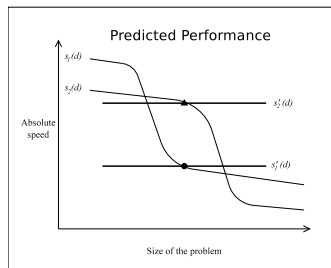


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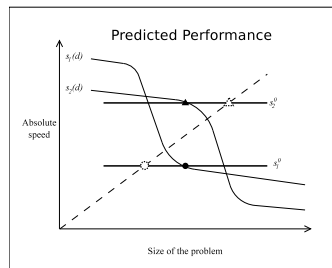
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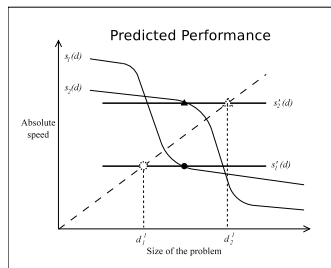
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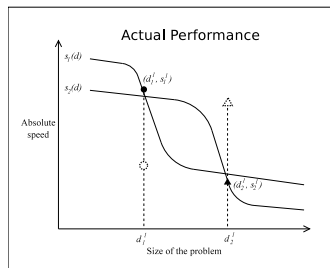
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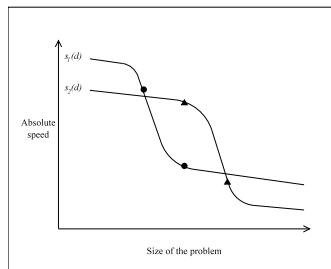
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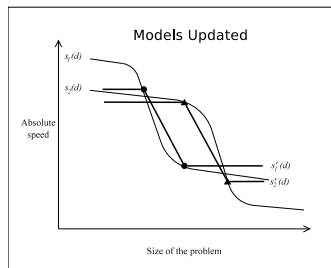
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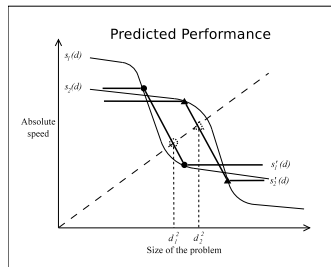
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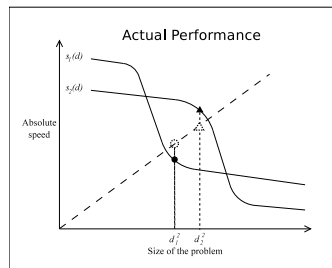
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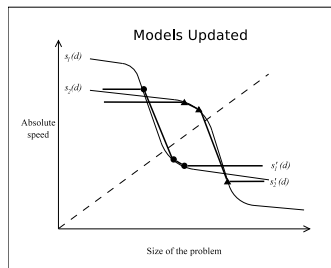
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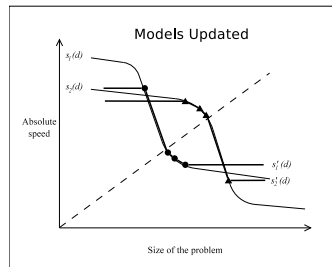
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Dynamic load balancing: Jacobi method

```

MPI_Comm_size(comm, &size);
// piecewise linear FPMs
supermod_model** models = malloc(sizeof(supermod_model*) * size);
for (i = 0; i < size; i++)
    models[i] = supermod_model_piecewise_alloc();
// current distribution, initially even
supermod_dist* dist = supermod_dist_alloc(D, size);
// context for dynamic load balancing
supermod_dynamic balancer = { supermod_partition_geometric,
    size, models, supermod_dist_alloc(D, size) };
// Jacobi data: dist->parts[i].d rows/els allocated for matrix/vectors
double *A = ..., *b = ..., *x = ...;
// main loop
while (error > eps) {
    // redistribution of Jacobi data: dist --> balancer.dist
    jacobi_redistribute(comm, dist, A, b, x, balancer.dist);
    // store the current distribution
    supermod_dist_copy(dist, balancer.dist);
    // iteration of Jacobi method
    gettimeofday(&start);
    jacobi_iterate(comm, dist, A, b, x, &error);
    // add new points (now-start) and balance the load
    supermod_balance_iterate(&balancer, comm, start);
}

```

API for dynamic partitioning and load balancing

Context of the dynamic algorithms

```
struct fupermod_dynamic {  
    fupermod_partition partition; // partitioning algorithm  
    int size;                     // number of procs  
    fupermod_model** models;      // current approximations  
    fupermod_dist* dist;          // current partitioning  
}
```

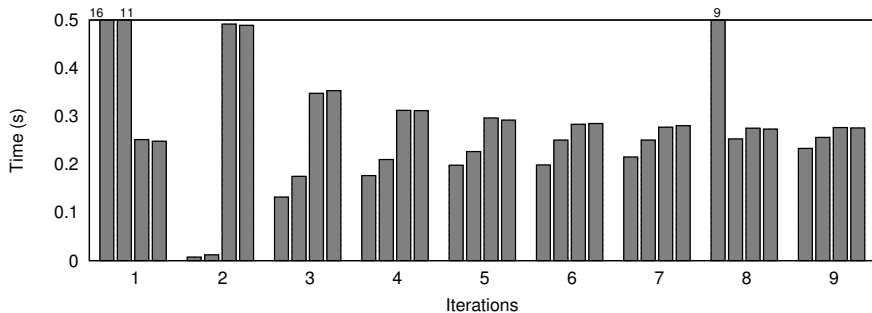
Dynamic data partitioning

```
// performs a benchmark  
int fupermod_partition_iterate(fupermod_dynamic*, MPI_Comm comm,  
    fupermod_precision precision, fupermod_benchmark* benchmark,  
    double eps);
```

Dynamic load balancing

```
// requires the start time as input  
int fupermod_balance_iterate(fupermod_dynamic*, MPI_Comm comm,  
    struct timespec start);
```

Dynamic load balancing on a heterogeneous cluster



Conclusion

FuPerMod: general-purpose data partitioning framework

- accurate and cost-effective performance measurement
- construction of computation performance models, using different methods of interpolation of time and speed
- invocation of model-based data partitioning algorithms for static and dynamic load balancing

<http://hcl.ucd.ie/project/fupermod>

Thank You!



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Complex HPC
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